

*Title:* INTEGRATING LINEAR INTERPOLATION FUNCTIONS  
ACROSS TWO AND THREE-DIMENSIONAL  
CELL BOUNDARIES

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# Integrating Linear Interpolation Functions Across Two- and Three-Dimensional Cell Boundaries

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## Objective

Develop *discrete expansions* for linear interpolation functions: expansions that are similar to a multivariable Taylor's series but — by accounting for discontinuous interpolation derivatives across cell boundaries — are valid throughout a discretized domain.

## Discrete Expansions for Linear Interpolation

### Total Differential

Total differential: a relationship between infinitesimal changes of the physical, logical, and cell-vertex coordinates  $d\bar{X} = f(d\bar{\xi}, d\bar{X}^{cv})$ :

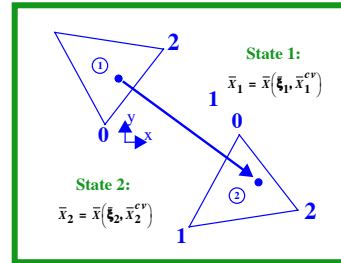
$$d\bar{X} = \frac{\partial \bar{X}}{\partial \bar{\xi}}(\bar{X}^{cv}) d\bar{\xi} + \frac{\partial \bar{X}}{\partial \bar{X}^{cv}}(\bar{\xi}) d\bar{X}^{cv}$$

Discrete-expansion: a relationship between the finite changes of these coordinates:  $\Delta \bar{X} = f(\Delta \bar{\xi}, \Delta \bar{X}^{cv})$ .

We integrate the total-differential between two particles located in separate, noncontiguous grid cells: State 1 and State 2.

$$\int_1^2 d\bar{X} = \int_1^2 \frac{\partial \bar{X}}{\partial \bar{\xi}}(\bar{X}^{cv}) d\bar{\xi} + \int_1^2 \frac{\partial \bar{X}}{\partial \bar{X}^{cv}}(\bar{\xi}) d\bar{X}^{cv}$$

Interpolation derivatives are generally not continuous across cell boundaries; original total-differential is not valid.



### Parameterization

Parameterize integration coordinate-space  $(\bar{\xi}, \bar{X}^{cv})$  with the variable 's', where  $0 \leq s \leq 1$ , using a linear technique:  $\phi(s) = (1-s) \phi_1 + (s) \phi_2$ .

$$\int_0^1 \frac{\partial \bar{X}(s)}{\partial s} ds = \int_0^1 \frac{\partial \bar{X}}{\partial \bar{\xi}}(\bar{X}^{cv}(s)) \frac{\partial \bar{\xi}(s)}{\partial s} ds + \int_0^1 \frac{\partial \bar{X}}{\partial \bar{X}^{cv}}(\bar{\xi}(s)) \frac{\partial \bar{X}^{cv}(s)}{\partial s} ds$$

Parameterized interpolation derivatives are continuous across cell boundaries; parameterized total differential is valid.

### Direct Integration Pathline

A straight or direct line between particle State 1 and State 2.

$$\Delta \bar{X} = \frac{\partial \bar{X}}{\partial \bar{\xi}}(\hat{\bar{X}}) \Delta \bar{\xi} + \frac{\partial \bar{X}}{\partial \bar{X}^{cv}}(\hat{\bar{\xi}}) \Delta \bar{X}^{cv}$$

Finite-difference vectors:  $\Delta \bar{X} = \bar{X}_2 - \bar{X}_1$ ,  $\Delta \bar{\xi} = \bar{\xi}_2 - \bar{\xi}_1$ , and  $\Delta \bar{X}^{cv} = \bar{X}_2^{cv} - \bar{X}_1^{cv}$ .

Particle end-state averages:  $\hat{\bar{\xi}} = (\bar{\xi}_1 + \bar{\xi}_2)/2$  and  $\hat{\bar{X}}^{cv} = (\bar{X}_1^{cv} + \bar{X}_2^{cv})/2$ .

### Upper-Step Integration Pathline

Partition the integration pathline in the  $(\bar{\xi}, \bar{X}^{cv})$  plane.

Integrate the upper-step pathline from State 1 to State A to State 2.

$$\Delta \bar{X} = \frac{\partial \bar{X}}{\partial \bar{\xi}}(\bar{X}_2^{cv}) \Delta \bar{\xi} + \frac{\partial \bar{X}}{\partial \bar{X}^{cv}}(\bar{\xi}_1) \Delta \bar{X}^{cv}$$

### Lower-Step Integration Pathline

Partition the integration pathline in the  $(\bar{\xi}, \bar{X}^{cv})$  plane.

Integrate the lower-step pathline from State 1 to State B to State 2.

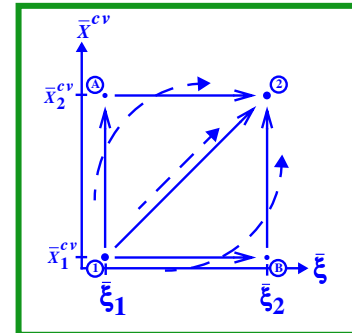
$$\Delta \bar{X} = \frac{\partial \bar{X}}{\partial \bar{\xi}}(\bar{X}_1^{cv}) \Delta \bar{\xi} + \frac{\partial \bar{X}}{\partial \bar{X}^{cv}}(\bar{\xi}_2) \Delta \bar{X}^{cv}$$

Upper-step and lower-step discrete expansions are mirror images.

Identical results for 2-D and 3-D linear-interpolation discrete expansions.

Discrete expansions acknowledge the full functional dependence of interpolation and inherently account for discontinuities across cell boundaries.

The total-differential method is a general solution technique for developing interpolation discrete expansions.



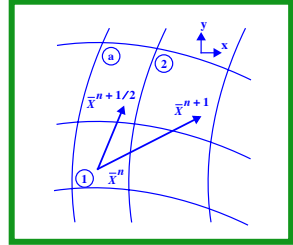
## Numerical Analysis

Analytical investigation of particle methods is used to establish the method's mathematical consistency and numerical accuracy.

Example: Predictor-Corrector time-integration for  $d\bar{X}/dt = \bar{V}(\bar{X}, t)$ .

Discrete expansions are required to relate interpolated velocities at State A to State 1:

$$\bar{V}(\bar{\xi}_a, \bar{V}_a^{cv}) = \bar{V}(\bar{\xi}_1, \bar{V}_1^{cv}) + \frac{\partial \bar{V}}{\partial \bar{\xi}}(\bar{V}_a^{cv}) \Delta \bar{\xi} + \frac{\partial \bar{V}}{\partial \bar{V}^{cv}}(\bar{\xi}_1) \Delta \bar{V}^{cv}$$



For computational models that use interpolation, discrete expansions represent a key advancement in the capability to analyze existing models and to develop advanced models.

## Logical-Coordinate Evaluation

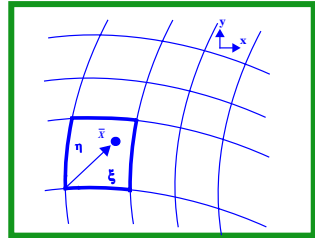
Spatial transformation of a particle-position vector from global, physical space  $\bar{X}$  to a local, cell-based coordinate system  $\bar{\xi}$ .

Discrete expansions are required to relate the known  $\Delta \bar{X}$  to unknown  $\Delta \bar{\xi}$ .

$$\frac{\partial \bar{X}}{\partial \bar{\xi}}(\bar{X}_2^{cv}) \Delta \bar{\xi} = (\bar{X}_2 - \bar{X}_1) - \frac{\partial \bar{X}}{\partial \bar{X}^{cv}}(\bar{\xi}_1) \Delta \bar{X}^{cv}$$

Solution characteristics:

- algorithmically robust (has a guaranteed nonsingular Jacobian matrix), and
- computationally efficient (derivatives are constant, including the Jacobian matrix).



## Summary

Discrete-expansions represent a key advancement for any particle method that uses interpolation by

- providing the capability to analytically define a method's mathematical consistency and numerical accuracy, and
- representing an algorithmically robust and computationally efficient method to locate particles within a grid.

## Next Development Step

Complete a similar total-differential discrete-expansion analysis for nonlinear interpolation: bilinear and trilinear functions.